Accurate Time & Frequency system for military applications

Use as an accurate Time & Frequency center for military platforms

The AR51A-09 unit is a compact GPS-Disciplined Rubidium Clock, which offers an excellent stability and accuracy. The unit includes a Rubidium-Atomic-Standard, which is phase-locked to the disciplining source (like GPS or other external inputs).

All outputs are derived from the Rubidium-Atomic-Standard and maintain highly accurate time and frequency even when GPS reception interrupted.

Key Features

- GPS disciplined Rubidium clock
- Frequency Accuracy : 1E-12
- 1PPS Accuracy: 30ns (RMS)
- Multiple outputs: 10MHz, 1PPS, TOD (Time of Day)
- TOD protocols: Have Quick, CLI
- Inputs: GPS antenna, 1PPS, TOD
- Holdover (no GPS): 1µs/24 hrs (typ.), 5E-11/month
- Monitor & Control: RS232 / RS422
- C/A code GPS receiver
- MIL-STD qualification for airborne applications
- Compact: 175 mm (d) x 132 mm (w) x 56 mm (h)

Options

- P(Y) code GPS (SAASM) receiver
- TOD : NMEA, NTP / PTP, IRIG B
- Monitor & Control: LAN (UDP, SNMP)
- NTP Client (Option)

Description

The AR51A-09 includes Time of Day (TOD) inputs and outputs. The standard unit include several Have Quick (ICD-GPS-060) Time Code outputs, followed by several (more than 20) 1PPS outputs (PTTI ICD-GPS-060, TTL and RS-422 formats) for accurate timing which is essential for secure radio communication applications. The standard unit includes also Have Quick (ICD-GPS-060) Time Code input for initial time loading followed by 1PPS input for the 1PPS timing synchronization, when the GPS signal is not available.

The communication with the unit is the CLI (Command Line Interface) by RS-232 or RS-422. The CLI outputs provides Time, Navigation and status data. The unit can be configured by CLI input channel.

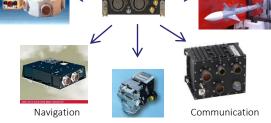
Other Time of Day formats are available as an option like NMEA, IRIG B, NTP or PTP.

The AR51A-09 can be synchronized from 3 independent inputs: internal GPS, external GPS and other external independent accurate timing systems. The input synchronization source is selected manually by user or automatically.

Standard option of the unit is LAN interface, which include NTP (Network Time Protocol), and Monitor & Control by UDP or by SNMP.

The AR51A-09 is designed for demanding military platforms such as fighter aircraft, helicopters, UAV's, ship borne, submarine and mobile land platforms. The unit is designed for quick installation on a tray or hard mount installation with screws.

The AR51A-09 Rubidium-GPS Clock system



Electronic Warfare

For Airborne, Ship borne & Land platforms

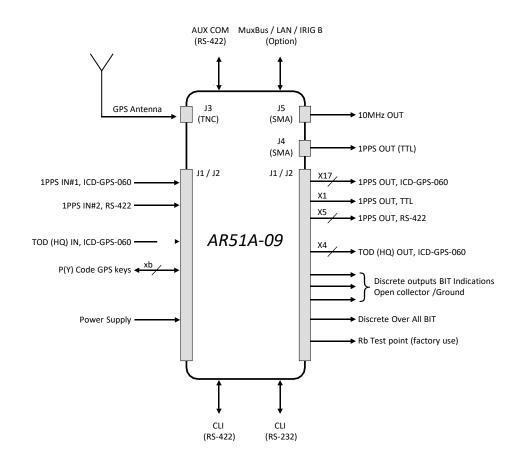




Specifications

	Input & Outputs	
	10MHz, Sine wave (8±3) dBm / 50W (x 1)	
	1PPS TTL/50Ω (x 2)	
	1PPS RS-422 (x 5)	
Outputs (*)	1PPS PTTI (ICD-GPS-060)/ 50Ω (x 17)	
		Options: NMEA, NTP server V3 per
	TOD Have Quick (ICD-GPS-060) / TTL 100KΩ (x 4)	RFC1305 ≤ 1ms, IEEE 1588 (PTP) – Grandmaster, IRIG B
	H/W BIT (open collector) (x 1)	
	TOD Have Quick (ICD-GPS-060) / TTL 100K Ω (x 1)	Options: NMEA, IEEE 1588 (PTP) – Slave, IRIG B
	1PPS TTL/50Ω or PTTI, ICD-GPS-060/ 50Ω (x 1)	
Inputs	1PPS RS-422 (x 1)	
	GPS Antenna	
CLI Communication	CLI – Command Line Interface, RS232 or RS422 for status monitoring and control for unit configuration Baud rate: 19,200, Control: 1, N, 8	Options: LAN – UDP & SNMP, MIL- STD- 1553RT (Mux-Bus)
MIL-GPS keys		Option: P (Y) code GPS receiver cryptokeys

(*) For other outputs contact factory.



Electrical Interface

		Performance				
Time (1PPS)	Long- Term Accuracy	Disciplined to GPS or to an external synchronization source	50ns RMS @ 25°C (Typical: 30ns RMS)			
11110 (111-3)	, , , , , , , , , , , , , , , , , , ,	Time drift without GPS (Hold-Over)	< ±1µs/24hr (typical)			
	Frequency Accuracy	Disciplined to GPS or to external 1PPS	< ±1E-12 (24 hours average)			
	Long Term stability	Frequency drift without GPS (Hold- Over / Aging)	±5E-11 / month			
	Short Term Stability (ADEV)	≤ 3E-11 @ 1s				
	Temperature	$\leq \pm 3E-10$ over -25°C to +6	\leq ±3E-10 over -25°C to +65°C (relative to +25°C)			
Frequency	Stability	(-40°C to +71°C available as an option)				
		Offset frequency [Hz]	Phase noise [dBc / Hz]			
	Phase Noise	10Hz	≤-114 dBc/Hz			
		100Hz	≤-140 dBc/Hz			
		1KHz	≤-140 dBc/Hz			
(10MHz)		10KHz	≤-150 dBc/Hz			
	Harmonics	≤-53 dBc (u	p to 90MHz)			
	Spurious	≤-100 dBc @ ± 100KHz from carrier				
		Rb Lock (< 1E-9) < 5 min				
	Warm-up (accuracy		ithin < 7 min			
	,		±5E-11 within < 60 min			
	vs. time)	±1E-11 within < 4hrs				
		±1E-12 wi	thin < 24 hrs			
	Retrace (without GPS or other disciplining input)	± 5	E-11			

GPS Receiver					
GPS Type	C (A) Code GPS receiver	P (Y) Code GPS receiver (option)			
GPS Tracking	L1 frequency 1575 MHz C/A code (SPS)12 parallel tracking channels.	L1/L2 frequency P(Y) code SAASM 12 parallel tracking channels			
Ephemeris & Almanac	Available (Option)				
Position Accuracy	Latitude, Longitude: < 6m (CEP 50%)Altitude: < 11m (CEP 50%)	PPS: < 12 m CEP			
Acquisition Time (Typical) (*)	Warm start ≤ 45 second Cold start ≤ 50 second (worst case)	Warm start ≤ 1 min (worst case) Cold start ≤ 12.5 minutes (worst case) ≤ 30 seconds when receiving the same satellites constellation (warm or cold start)			
Internal backup battery	N / A	Keeping Ephemeris & Almanac. The receiveruses the battery for saving the data for non-operating accumulative duration of about 2years.			
GPS Antenna DC Voltage					

The P (Y) code GPS receiver must be supplied by user

Environmental					
	Operating :- 25°C to +65°C (option for -40°C to +65°C)				
-	Emergency: +71°C for 30 minutes				
Temperature	Storage : -40°C to +85°C (option: lower storage temperature of -46°C. Been tested in modelAR51A009-W0L00)				
Temperature Altitude	0 to 50,000 ft				
Humidity	95% non condensing				
Random Vibration	2.45gRMS as per the following profile:				
Mechanical Shock - Operation	MIL-STD-810C/E, Method 516.2, Proc. 1 (30g / Half sine / 3 axis / 6 shocks per axis(
Mechanical Shock - Crash	X-40G, Y-15G, Z-20G, 11ms, Half Sine, Total 12 shocks				
Bench Handling Shock	MIL-STD-810F, Method 516.5, Procedure VI				
Rain	MIL-STD-810E Method 506.3 procedure I				
Dust	MIL-STD-810E Method 510.3				
Salt Atmosphere	MIL-STD-810E, Method 509.3, Procedure I				
Bonding	≤2.5 mΩ				
EMI / RFI	MIL-STD-461B/C Part: 5 (CE01, CE03, CE07, RE02, CS01, CS02, CS06, RS02, RS03)				

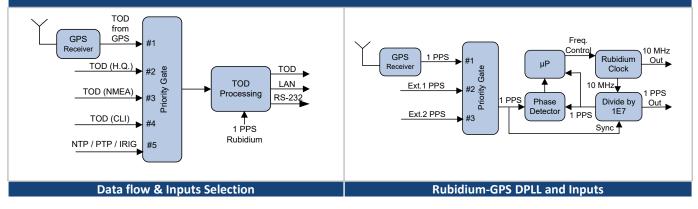
Power Supply				
Input Voltage	22-32 VDC (28 VDC Typ.) per MIL-STD-704D			
	< 30 W @ 28 VDC (warm-up)			
Power consumption	< 16 W @ 28 VDC @ 25°C (steady-state)			
	< 20 W @ 28 VDC @ -25°C (steady-state)			

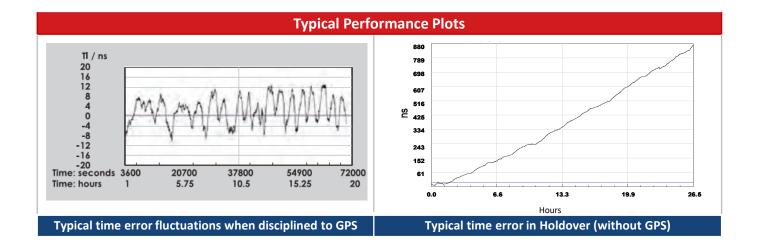
Reliability, Maintainability, Testability					
MTBF	> 16,000 hours @ 30°C, ARW, MIL-HBK-217F (for C/A GPS receiver)				
WILDF	> 3,700 hours @ 30°C, ARW, MIL-HBK-217F (for P/Y GB-GRAM)				
MTTR – O Level	12 minutes to replace failed unit (including warm-up time)				
BIT (Built In Test)	On-line BIT – Automatic, Covers > 90% of all failures				

Dimensions & Weight					
Dimensions	175 mm (d) x 132 mm (w) x 56 mm (h)				
	C / A code GPS receiver	≤ 1.2 Kg			
Weight	C / A code GPS receiver and LAN / 1553 board:	≤ 1.3 Kg			
	P / Y code GPS receiver, back up battery and LAN / 1553 board	≤ 1.5 Kg			

Principles of Operation

The following block diagrams depict the operation of the AR51A-09. The unit includes Rubidium Standard and accepts Input from internal GPS receiver, external 1PPS or external TOD (H.Q). All outputs are derived from the internal Rubidium Clock, which is phase locked by a digital PLL to the selected input. Thus, the Rubidium Clock - frequency and time - follows the GPS on the long term average. If GPS reception is lost for short or long periods of time the Rubidium Clock shall maintain accurate time and frequency with no phase interruption.



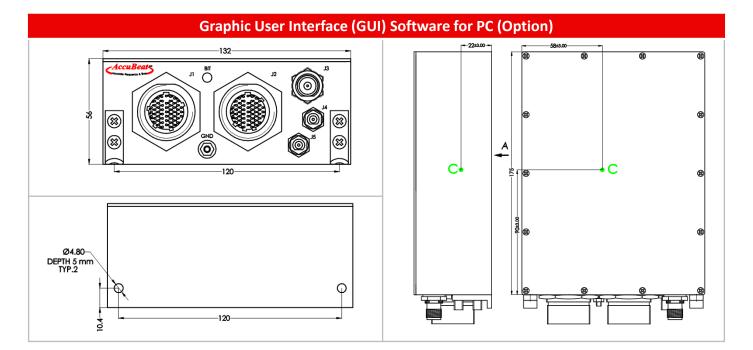


Graphic User Interface (GUI) Software for PC (Option)

GUI for PC is available: parameters settings (like: time, date, unit configuration etc'), monitoring (like: BIT status) and data presentation (like: time, date, position etc')

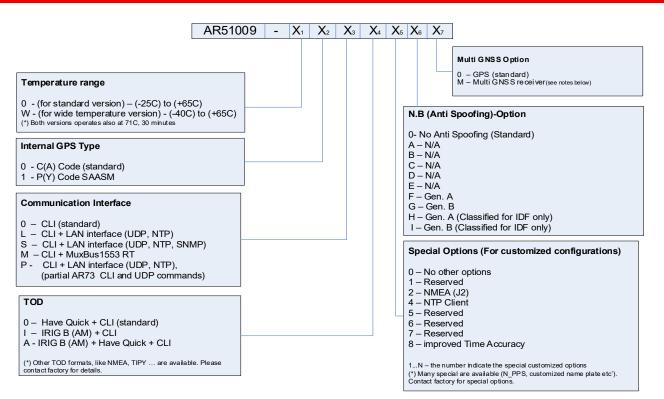
COMM S	Dawartabo	Parity	File Descriptio	on E	inable Time Stamp PC Time Stamp	Save
Day 299	Time 13:16:40.00	Date 25/10/2012	Time mode UTC	TFOM GPS offset	General BIT	Open Terminal
Time Sou GPS Last Time	e Source	Sync. Source GPS Last Sync. Source	—	. 1PPS 1PPS IRIG . Freq. Ext. NMEA		Close Terminal
Auto Num of s 8 Sat in vie	Time Source at	Hold over Selected Sync. Source Auto Quality Indicator C/A type	Latitude 31:48.1036N HDOP VDOP 1.1 0.0	Longitude 035:12.6847E PDOP TDOP 0.0 0.0	Altitude +769.5 Altitude Type MSL	Time Error Sou N.A. Time Error 0 12:48:08.00 12:49:25:00

Time Report T	ime Set up & B	IT Report C	onfiguration	1 & Matrix Setup		AccuBeat
BIT Report					10	Read Parameters
GPS Input	Ext. NMEA	A7 Status	1.2V	Antenna Current	Time & Date Set Rx	Reading
Ext. 1PPS	RTC Time	A9_1 Status	2.5V	23	13:50:00 15/05/2011	
Ext. Freq.	A2 Status	A9_2 Status	5V	Internal Temp 39	Start Date Stop Date Autom	Table of contente
Ext. TOD	A3 Status	A9_3 Status	15V	39		auc i i i i i i i i i i i i i i i i i i i
IRIG B 1PPS	A5 Status	A12 Status	Antenna	Status	11/07	Fail
Setup Report	t					
Time Source		1PPS Source Auto		Time Mode		ay Output Delay
GPS offset L	eap second No event 🗊	GPS Type. GB-GRAM		Altitude 🗌 A3 Enables		Pubidum
Time Zone	Time Source M Input TOD	ode NTP Mode UTC Time	C	Time Report A9_1 Time Report	Start date Stop date Aotuma 00:00:00 00:00:00 Dayligh	
Display mode ON	Display Timeo 60	ut Time Repor	tCLI (A9_2 Time Report	DDS Freq. DDS Factor 10000000.000000 1 DDS	S Enabled



	Electrical ICD		
Connector	Description	I/O	
	1PPS RS422 outputs x 4		
	1PPS RS422 Input x 1		
	1PPS TTL output x 1		
	Have Quick outputs x 2		
14	Have Quick input x 1		
J1	CLI RS-232 (Rx, Tx)	In / Out	
	LAN / MuxBus		
	Over all BIT indication x 1		
	P (Y) code GPS receiver crypto keys		
	Power supply		
	1PPS RS422 output x 1		
	1PPS PTTI input x 1		
J2	1PPS PTTI outputs x 17	In / Out	
	Have Quick output x 2		
	CLI RS422 x 1		
	GPS antenna input		
J3	1.5GHz, TNC, Female	In / Out	
	5V DC – out for active antenna		
J4	1PPS , TTL / 50 Ω , SMA, Female	Out	
J5	10MHz, Sine-wave, 8 \pm 2dBm, 50 Ω , SMA, Female	Out	

HOW TO ORDER



Please note that not all combinations may be possible. Please contact AccuBeat for further information

Notes:

1. Multi GNSS supports GPS, GLONAS, GALILEO and BEIDU constellation.

ACCESSORIES

For Accessories like GPS antenna, antenna cable, tray with vibration isolator, GUI etc. contact factory.

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